

CRYSTALLIZATION FOULING WITH ENHANCED HEAT TRANSFER SURFACES

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ABSTRACT

The main aim of this paper is to demonstrate that a simple stirred batch cell can be used to study the effects of surface shear stress (amongst other process parameters) on fouling from saturated calcium sulphate and calcium carbonate solutions. Fouling tests have been conducted using heated probes fitted with both smooth and enhanced surfaces. For otherwise identical operating conditions, the overall fouling rate on a mild steel surface was found to be reduced when either fine wires were attached to it or when helical threads were incorporated into the surface, either in the form of a continuous helical groove or in the form of a raised helix. The raised helical surface was more effective in reducing fouling than the helical groove. The results confirm the general effect that fouling rates can be reduced by increasing the surface shear stress through surface enhancement. The potential weakness of the stirred batch cell compared with a continuous flow loop apparatus is that the former cannot be operated at steady state conditions. Hence a simple mathematical model has been developed to take into account the dynamic change in bulk concentration as crystallization fouling occurs. In all cases, the overall fouling resistance increased asymptotically towards a constant value and could easily and accurately be described quantitatively by the new analytical model. The variations of shear stresses on the various surfaces were determined from CFD simulations using the commercial package Comsol 4.2.

INTRODUCTION

Crystallization fouling on heat exchanger surfaces can create chronic operational problems in a broad range of processing applications that include cooling water systems, desalination, steam generation, etc. Energy losses, additional power consumption and the costs of cleaning all make this practical operational problem a significant challenge in the progression towards sustainable development.

Several researchers have investigated crystallization fouling of calcium sulphate and calcium carbonate using recirculating tubular flow type devices (eg Malayeri et al., 2007, Fahiminia et al., 2007, Albert et al., 2009, and Esawy et al., 2009). The effects of a number of operational parameters such as velocity, temperature, calcium concentration, and surface geometry on the fouling rate have been studied. In the research presented in this paper, a different approach has been adopted. The simple stirred batch cell which was originally designed to study fouling from crude oils (Young et al., 2011) has now been used for the first time to study the effects of surface shear stress and surface temperature on fouling from saturated calcium salt solutions. The principal advantage of the batch cell over its continuous flow counterpart is that different surface configurations that enhance turbulence and heat transfer can easily be studied. The effects of enhancements such as wires, dimples, helical threads, etc, on fouling can then be interpreted to assist prediction of the effects of surface enhancements on fouling in, for example, plate heat exchangers and tubes fitted with inserts such as hiTRAN. A disadvantage of the stirred batch cell, given that the volume of solution is small (about 1 litre), is that the concentration of calcium salt may not be considered to be constant due to the formation of crystallization deposits on the heated surface. The fouling rate is therefore dynamically related to the change in bulk concentration with time. This clearly sets a challenge when interpreting the experimental data, but on the other hand, initial fouling rates arise at the known initial bulk concentration and of course the data may provide an excellent opportunity to discover the effect of bulk concentration on fouling rate in a single simple experiment.

Apart from determining fouling resistances through interpretation of the heat transfer data, the actual fouling layer profiles have also been studied using a ProScan laser micro-scanning technology. In addition, the experimental data are complemented by CFD simulations of the fluid flow in the stirred cell in the manner described elsewhere (Yang et al., 2009). The CFD studies have been made for

test probes with and without surface enhancements using the commercial package Comsol 4.2. The resulting velocity, shear stress and temperature fields are able to show clearly how the experimental effects of temperature and surface shear stress on the fouling are well correlated by the CFD simulations.

EXPERIMENTS

The stirred cell and probes

Details of the stirred cell system and the heated test probe shown in Figure 1a are provided by Young et al. (2011). The cell comprises a pressure vessel made in-house from a block of 304 stainless steel and is fitted with a top flange. The base of the vessel houses an upwards pointing test probe heated internally by a cartridge heater. The heat flux is controlled electrically. A batch of about 1.0 litres of aqueous solution is agitated by a downwards facing cylindrical stirrer mounted co-axially with the test probe and driven by an electric motor. External band heaters are incorporated to provide initial heating to the vessel and its contents. An internal cooling coil uses a non-fouling fluid (Paratherm) to remove heat at the rate that it is put in via the cartridge heater during the fouling run. The vessel is fitted with a pressure relief valve and there is a single thermocouple to measure the bulk solution temperature. The mechanisms for the control of bulk temperature and stirring speed are described elsewhere (Young et al., 2011). The surface temperature of the test probe can be changed by altering the heat flux by adjusting the input power to the cartridge heater.

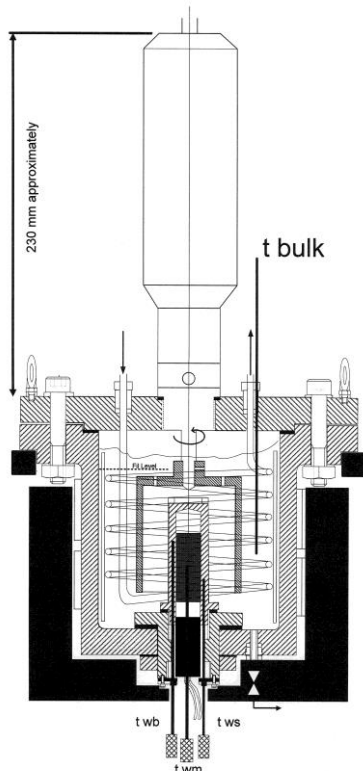


Fig. 1a The stirred batch cell
twb, twm, and tws are thermocouples

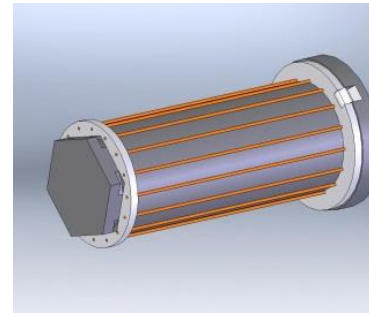


Fig. 1b The fouling probe fitted with a nest of wires
(Yang et al., 2013)

Details of the plain mild steel probe and the one fitted with a nest of wires, as shown in Figure 1b, respectively, have been reported elsewhere (Yang et al., 2013). The probe has, additionally, been modified by attaching sleeves with helical threads incorporated into their surface, either in the form of a continuous helical groove or in the form of a raised helix. Figures 2a and 2b show the two helically enhanced sleeves with negative and positive helices, respectively, and Figure 2c shows, as a reference, a plain sleeve of the same diameter as the two helically enhanced ones.

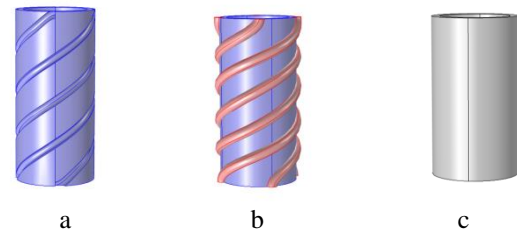


Fig. 2 Probe sleeves
a: Sleeve with negative helical thread
b: Sleeve with positive helical thread
c: Plain sleeve

Materials and experimental method

The purpose of this paper is to confirm that the stirred batch cell can be used to study the effects of enhanced surfaces on fouling from aqueous solutions. For this purpose, simple standard solutions of calcium sulphate and calcium carbonate have been used. This study is not concerned with studying the effects of water chemistry on the fouling process. The standard solution of CaSO_4 is prepared by dissolving 4.1g of $\text{Ca}(\text{NO}_3)_2$ and 8.0 g of $\text{Na}_2\text{SO}_4(\text{H}_2\text{O})_{10}$ (both from Sigma-Aldrich) in 500 ml of deionized water, and then mixing the two solutions to form a 1 litre working solution containing 3400 ppm of CaSO_4 at pH=5.6. The standard solution of CaCO_3 is prepared by dissolving 1.68 g of NaHCO_3 and 1.44 g of $\text{CaCl}_2(\text{H}_2\text{O})_2$ (both from Sigma-Aldrich) in 500 ml of deionized water, and then mixing the two solutions to form a 1 litre working solution containing 1000 ppm of CaCO_3 at pH=5.2. For working solutions at other concentrations, the mass of each chemical is adjusted proportionately. All chemicals are reagent grade. The working solution is transferred to the stirred batch cell and brought up to the desired bulk operating temperature by means of the external band heaters

with the solution being stirred by the cell's internal rotor. Subsequently, the test probe is brought up to the desired surface temperature. The two heating sources and a PID-controlled cooling circulator work together and maintain the thermal steady state for the stirred cell. The operating conditions for data reported in this paper are provided in Table 1.

At the end of a fouling run, the stirred batch cell is cooled and the probe is removed. After drying, the probe is held within a V block and placed in the measuring plate of the ProScan 2000 instrument (Scantron Industrial Products Ltd, Taunton, UK). The surface of the probe is scanned using a laser optical sensor to measure the thickness profile of the fouling layer.

Table 1 Operating Parameters

Operational parameter	Range
Bulk temperature (°C)	50 - 60
Average heat flux (kW m^{-2})	30 - 152
Surface temperature (°C)	70 - 95
Stirring speed (rpm)	60 - 400
Pressure (bar)	1 - 1.5

CFD SIMULATION

CFD and heat transfer simulations are carried out using Comsol Version 4.2a. The model geometry is set up to be three dimensional. The boundary conditions are wall functions for all solid-fluid boundaries, boundary layer heat sources for the cartridge heater and the band heaters, and variable temperature depending on the position from bottom to top for the cooling coil, respectively. The physical model is non-isothermal flow in a turbulent mode. Justification of the flow mode has been provided earlier (Yang et al., 2009).

RESULTS AND DISCUSSION

Fouling resistance

The stirred batch cell is operated at constant bulk temperature and constant heat flux. Hence, the rate of fouling is directly proportional to the rate of change of surface temperature with time, with the assumption that as the deposit grows the film heat transfer coefficient remains constant (Young et al., 2011).

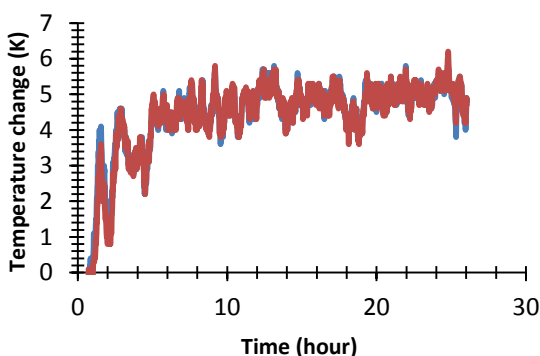


Fig. 3 Typical fouling curve for a stainless steel probe
 Red line: temperature by twm;
 Blue line: temperature by twb
 Stirrer speed: 150 rpm; bulk temperature: 55°C;
 average heat flux: 31 kW m^{-2}

Typical CaSO_4 curves for the difference between probe metal temperature and bulk temperature (for two thermocouple locations in one run) are shown in Figure 3. To convert the temperature difference to the fouling resistance, the heat flux at each thermocouple location needs to be determined instead of using the heat flux averaged over the whole of the probe surface. This is important because neither the surface temperature nor the heat flux is uniform vertically along the heated probe surface. The local heat flux can be obtained by means of CFD simulation. Figure 4 shows the CFD-predicted temperature field in the stirred cell and Figure 5 shows a comparison of the CFD-predicted surface temperatures with the measured values, thereby partially validating the CFD simulation.

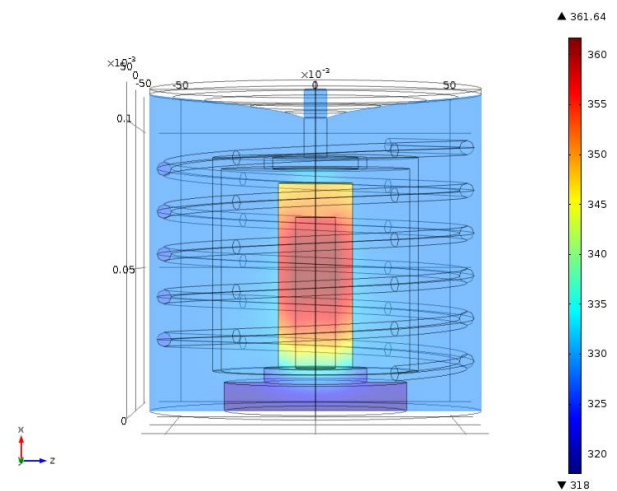


Fig. 4 Temperature field in the stirred cell
 Heater power: 130 W; stirrer speed: 300 rpm;
 bulk temperature: 55°C

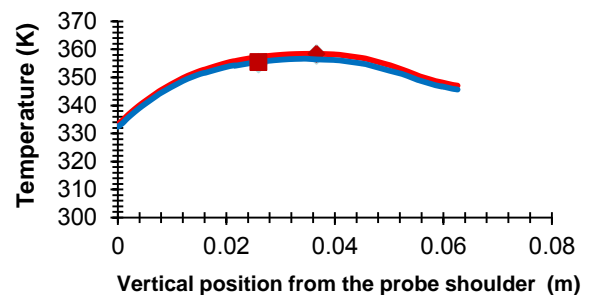


Fig. 5 Vertical temperature profiles over the probe surface and over the vertical line where thermocouples are located.
 Blue line: probe surface temperature by simulation;
 Red line: temperature over the vertical line where the thermocouples are located by simulation;
 ■: temperature reading by twm;
 ◆: temperature reading by twb
 Stirrer speed: 130 rpm; bulk temperature: 55°C;
 average heat flux: 31 kW m^{-2}

Figure 6 shows the vertical profile of the heat flux over the probe surface. The local heat flux can also be determined using the heat transfer coefficient, which may be assumed to be constant over the probe surface, given that it has been shown that the surface shear stress is relatively

uniform over the probe surface when it is not enhanced (Yang et al., 2009). The local heat flux data were then used to calculate the fouling resistance using the temperature difference data such as that shown in Figure 3. Typical fouling curves in terms of how the fouling resistance varies with time are shown in Figures 7a and 7b for CaSO₄ and CaCO₃, respectively.

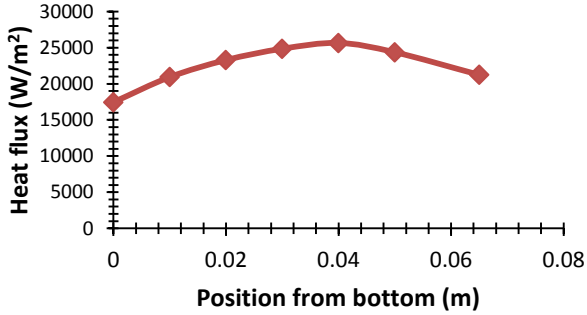


Fig. 6 Heat flux profile over the probe surface (stainless steel probe)
Heating power: 130W; stirrer speed: 310 rpm;
bulk temperature: 55°C

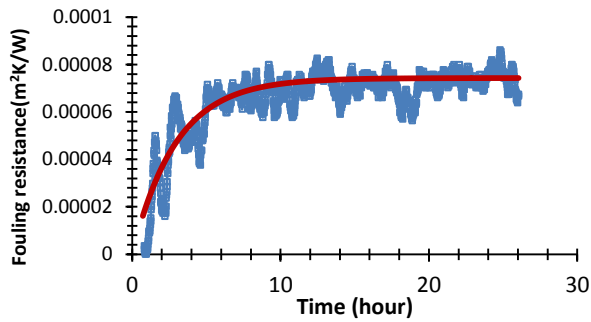


Fig. 7a Fouling resistance data of CaSO₄ and model fit (stainless steel probe)
Symbols: experimental data derived from twb;
Line: model fitting
Stirrer speed: 150 rpm; bulk temperature: 55°C;
average heat flux: 32 kW m⁻²

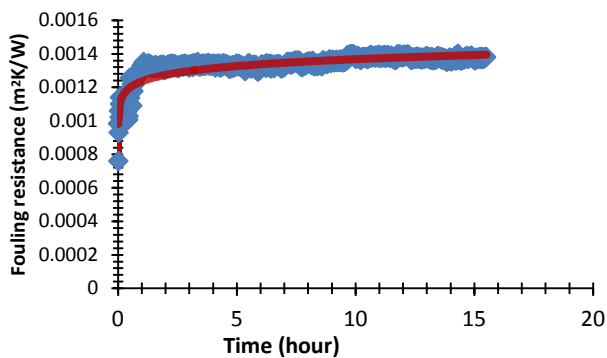


Fig. 7b Fouling resistance data of CaCO₃ and model fit (stainless steel probe)
Symbols: experimental data derived from twb;
Line: model fitting
Stirrer speed: 150 rpm; bulk temperature: 55°C;
average heat flux: 33 kW m⁻²

Effect of bulk concentration

Figures 7a and 7b show that the fouling resistances seem to reach asymptotic values relatively quickly. On the one hand, the net fouling rate which many consider to be the difference between a deposition rate and a removal rate can be considered to be reducing gradually towards zero up to the asymptote. On the other hand, further analysis reveals that this asymptotic situation could be caused by the gradual reduction in the driving force for crystallization as time progresses in the batch system. That is, as deposition progresses then the degree of super-saturation, due to the calcium salt leaving the bulk solution and depositing on the heated surface, causes a reduction in the bulk concentration. As an example of the potential magnitude of this concentration depletion effect, the dry mass of deposit after one fouling run was found to be 0.97 g, accounting for about 30% of the original salt mass in the bulk solution. If this is the cause of the asymptotic curves shown, for example, in Figures 7a and 7b, then traditional asymptotic models may not be applicable and the dynamic change in bulk solution must, accordingly, be taken into account. Fahiminia et al. (2007) developed a fouling rate model after Konak (1974) and Krause (1993) that gives a relationship between the initial fouling rate and the difference in concentration between super-saturation in the bulk and in normal saturation:

$$\Phi = \frac{\Delta C}{\frac{1}{k_m} + \frac{1}{k_a^{1/n}} - \Phi^{(n-1)/n}} \quad (1)$$

Here Φ is the crystallization deposition rate, $\Delta C = C_b - C_s$ is the difference in concentration between the super-saturation in the bulk, C_b , and the normal saturation, C_s . Additionally, k_m , k_a , and n are the mass transfer coefficient, reaction rate constant, and reaction order, respectively. The fouling rate is related to Φ after Fahiminia et al. (2007), as follows:

$$\frac{dR_f}{dt} = \frac{\Phi}{\lambda_f \rho_f} \quad (2)$$

Here, λ_f and ρ_f are the thermal conductivity and density of the fouling deposit, respectively. Assuming that the bulk concentration reduction caused by fouling is proportional to the fouling resistance, then the change in bulk concentration is given by:

$$C_b = C_{b0} - \alpha R_f \quad (3)$$

In equation (3), C_{b0} is the initial bulk concentration and α is a constant. Given that $\Delta C_0 = C_{b0} - C_s$, then by combining equations (1), (2), and (3), by assuming that $n = 1$, and by taking into account a deposit removal term, as proposed by Crittenden et al. (1987), equation (4) is obtained:

$$\frac{dR_f}{dt} = \frac{\Delta C_0 - \alpha R_f}{\frac{1}{k_m} + \frac{1}{k_a}} - \gamma R_f \quad (4)$$

Here γ is the rate constant of any deposit removal process which would depend critically on both temperature and velocity (or surface shear stress). The equation is broadly similar to that developed for a model organic fluid system by Crittenden et al. (1987). Integration of equation (4) yields:

$$R_f = \frac{\Delta C_0}{\alpha + \frac{k_m - k_a}{k_m k_a} \gamma \lambda_f \rho_f} \left[(1 - \exp \left(- \left(\frac{\alpha}{\lambda_f \rho_f} \frac{k_m k_a}{k_m - k_a} + \gamma \right) t \right) \right] \quad (5)$$

As shown in Figures 7a and 7b, the calcium salt fouling curves obtained using the stirred cell are correlated well using equation (5). The equation shows correctly that R_f is zero at $t = 0$, and that the fouling resistance tends towards a constant value when the running time is sufficient, appearing to give a fouling curve of the asymptotic type. The maximum value of R_f is proportional to the difference in concentration between the initial bulk super-saturation and the normal saturation. The initial fouling rate can be obtained by differentiation of equation (5), setting $t = 0$, or simply using equation (4) and setting $R_f = 0$, at $t = 0$:

$$\frac{dR_f}{dt} = \frac{\Delta C_0}{\lambda_f \rho_f} \frac{k_m - k_a}{k_m k_a} \quad (6)$$

According to equation (6), the initial fouling rate is proportional to the initial difference in concentration between the initial super-saturation and the normal saturation. Figure 8 shows four initial fouling rates for CaSO_4 at different initial concentrations, keeping all other operating parameters constant. Figure 8 indeed shows that the initial fouling rate is linearly dependent on the difference in concentration between the initial super-saturation and the normal saturation, as given by equation (6).

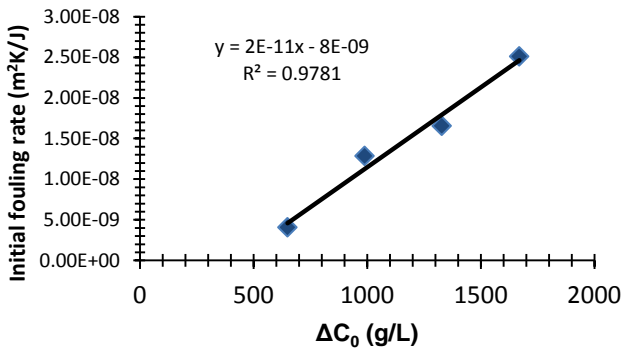


Fig. 8 Linear dependency of initial fouling rate on the difference in concentration between initial super-saturation and normal saturation
 $\Delta C_0 = C_{b0} - C_s$
 with $C_s = 2.070 \text{ kg m}^{-3}$ (Calmanovici et al., 1993)

Effect of temperature

In general, fouling is more intensive when the surface temperature is higher. As shown in Figures 4 and 5, the surface temperature of the heated probe is higher in the middle and lower towards its two ends. This variation arises

as a result of the complex fluid flow patterns within the inner boundary of the batch cell’s stirrer.

Figure 9a shows a photograph of the probe with a scaling deposit, and Figure 9b shows the deposit thickness profile along the vertical length obtained using ProScan 2000. It can be seen that the fouling layer thickness profile over the probe surface is strikingly similar in form to the temperature profile shown in Figure 5, with maxima in both deposit thickness and temperature occurring near to the middle of the heated probe surface. As reported previously (Yang et al., 2009), the shear stress over the probe surface where the fouling zone is located is relatively constant. Hence the profile of the fouling behaviour is determined solely by the surface temperature and not the shear stress. Accordingly, the similarity of the temperature and the fouling layer thickness profiles can be used to explain qualitatively the fouling rate behaviour in the experiment as a function of surface temperature.



Fig. 9a Mild steel probe with CaSO_4 deposit

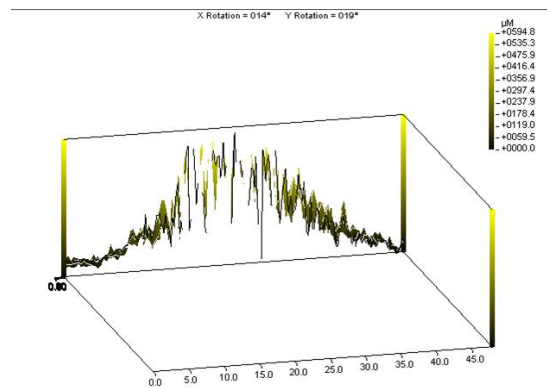


Fig. 9b ProScan deposit thickness profile

Effect of surface enhancements on fouling

The overall fouling rate on a mild steel surface was found to be reduced when fine wires were attached to it. Under the same operational conditions of bulk temperature (55°C), initial surface temperature (88°C) and stirrer speed (300 rpm), the fouling rates on the wired probe and the bare probe were $2.9 \times 10^{-5} \text{ m}^2 \text{ K J}^{-1}$, and $4.2 \times 10^{-5} \text{ m}^2 \text{ K J}^{-1}$, respectively. Furthermore, as shown in Figure 10, the fouling rates on the probes fitted with helical surfaces (both negative and positive) were found to be lower than on the

smooth surface. Moreover, the fouling rates on the positive helical surface were found to be the lowest. These reductions in fouling rate with enhanced surfaces are caused by the enhanced turbulence created either by the attached wires or by the incorporated helical threads. As shown in Figure 11, the shear stress is higher over the surface of the wired probe than over the bare probe. In the cases of probes fitted with sleeves, the average shear stress was found to increase in the order of smooth surface, negative helical groove, and positive helical surface, as shown in Figure 12. The difference in fouling rate on the different surface configurations can therefore be explained using the shear stress data obtained by CFD simulation.

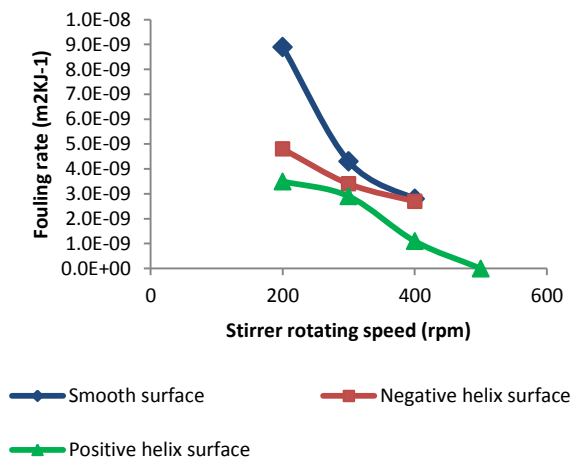


Fig. 10 Fouling rates of CaCO₃ on smooth, negative and positive helical surfaces; bulk temperature: 55°C

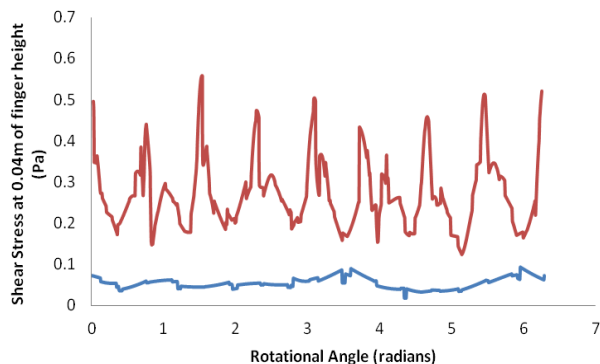


Fig. 11 Comparison of shear stress over the wired probe surface – around a circle (0 - 2 π)
Stirrer speed: 200 rpm; bulk temperature: 55°C

It can be seen from Figure 13 that when wires are present the distribution of fouling is non-uniform. Indeed, the greatest amount of fouling appears downstream of the wires where the surface shear stress is the lowest (Figure 11) and the least amount appears just upstream of the wires where the surface shear stress is the highest. Given the clockwise flow direction, the shear stress is higher in front of a wire than behind it. This may suggest that fouling is more likely behind the wire, and this is confirmed by Figure 13.

At present it is not possible to measure surface shear stresses directly in the stirred cell. Nonetheless, values of the shear stress obtained by CFD simulation can be compared with those inside a round tube. This leads to the concept of equivalent velocity (Yang et al., 2009) which is the velocity inside a round tube that gives the same surface shear stress as in the geometry under study (here, the batch stirred cell). In the present case, the equivalent tube flow velocity of water lies in the range 0.05 to 0.5 m s⁻¹ for the shear stress levels shown in Figure 12.

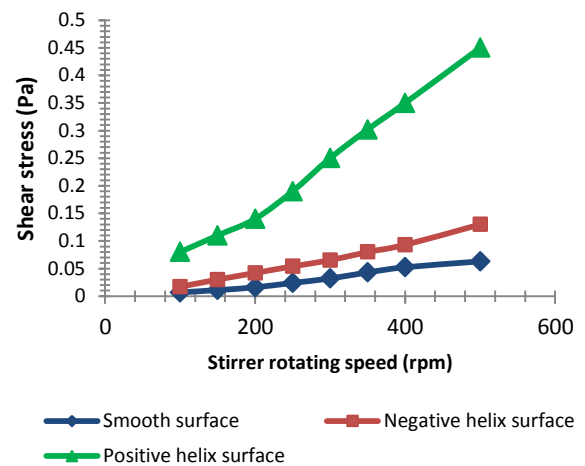


Fig. 12 Average shear stress on smooth surface, negative and positive helical surfaces



Fig. 13 Photograph of the wired probe after CaSO₄ fouling test; fluid flows clockwise when viewed from the top

CONCLUSION

The stirred batch cell fouling has been used to make preliminary investigations of the effects of surface shear stress, surface temperature, and starting bulk concentration on calcium sulphate and calcium carbonate fouling. The paper demonstrates the flexibility and adaptability of the cell over its continuous flow counterpart, thereby offering a facility in which ways to mitigate fouling problems can be studied quickly. The potential weakness of the stirred batch cell is that it cannot be operated at steady state conditions. Hence, a model has been developed to take into account the dynamic change in bulk concentration as scaling occurs. The experimental results show that calcium salt scaling can

be mitigated to some extent by changing the turbulence structure by means of attaching wires or incorporating helical threads into the heat transfer surface. This augurs well for mitigation of scaling by adding inserts into tubular flow systems or by surface corrugation. The scaling behaviour can only be interpreted properly with the help of CFD simulation since it is essential that an understanding of the effect of shear stress is available. Given that the work reported in this paper focuses only on developing a methodology for interpreting fouling data in a stirred batch cell as well as on the effects of enhanced surfaces, the effect of the chemistry of calcium salt solutions has not been addressed here, but could be the subject for further research.

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NOMENCLATURE

C	CaSO ₄ concentration, g/L or kg m ⁻³
C_b	CaSO ₄ bulk concentration, kg m ⁻³
C_{b0}	CaSO ₄ initial bulk concentration, kg m ⁻³
C_s	CaSO ₄ saturation concentration, kg m ⁻³
ΔC	$C_b - C_s$, kg m ⁻³
ΔC_0	$C_{b0} - C_s$, kg m ⁻³
k_a	surface reaction/attachment rate constant, m ⁴ kg ⁻¹ s ⁻¹
k_m	mass transfer coefficient, m s ⁻¹
n	reaction order
R_f	fouling resistance, m ² k W ⁻¹
t	time, s and hour

Greek symbols

α	model constant, kg m ⁻⁵ K ⁻¹ W
ρ_f	fouling deposit density, kg m ⁻³
λ_f	fouling deposit thermal conductivity, W m ⁻² K ⁻¹
γ	deposit removal rate coefficient, s ⁻¹
Φ	deposition flux, kg m ⁻² s ⁻¹

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